

WEST Search History

DATE: Wednesday, May 24, 2006

Hide?	<u>Set</u> <u>Name</u>	<u>Query</u>	<u>Hit</u> <u>Count</u>
	<i>DB=PGPB,USPT,JPAB; PLUR=YES; OP=OR</i>		
<input type="checkbox"/>	L29	L28 and (constrain\$ same nonlinear same programming)	10
<input type="checkbox"/>	L28	L27 and (optimal or optimum or feasi\$)	30
<input type="checkbox"/>	L27	L26 and ((local and global) same search\$)	30
<input type="checkbox"/>	L26	L3 or l4	399
<input type="checkbox"/>	L25	L1 and l4	0
<input type="checkbox"/>	L24	L22 and (search\$ same (trajector\$ or path or direction))	38
<input type="checkbox"/>	L23	L22 and (search\$ same (trajector\$ or path))	16
<input type="checkbox"/>	L22	l4 and (constrain\$ same nonlinear)	184
<input type="checkbox"/>	L21	L19 and ((trajectory or path or direction) same search)	8
<input type="checkbox"/>	L20	L19 and (trajectory or path or direction)	20
<input type="checkbox"/>	L19	L18 and search	20
<input type="checkbox"/>	L18	L13 and (constrain\$ same (nonlinear or (non adj linear\$)))	20
<input type="checkbox"/>	L17	L14 and (virtual same machine)	26
<input type="checkbox"/>	L16	L14 and (graphical same process\$)	36
<input type="checkbox"/>	L15	L14 and (graphical adj process\$)	0
<input type="checkbox"/>	L14	embed\$ adj microcontroller	819
<input type="checkbox"/>	L13	L9 and feasib\$	26
<input type="checkbox"/>	L12	L9 and feasab\$	0
<input type="checkbox"/>	L11	L10 and embed\$	1
<input type="checkbox"/>	L10	10439440	1
<input type="checkbox"/>	L9	l8 and cost	43
<input type="checkbox"/>	L8	L7 and (constrain\$ or unconstrain\$)	50
<input type="checkbox"/>	L7	l4 and dynamic\$ and search and (traject\$ or path) and (optimal or optimum)	54
<input type="checkbox"/>	L6	l4 and dynamic\$ and traject\$ and (optimal or optimum)	51
<input type="checkbox"/>	L5	L4 and (optim\$ adj global\$)	5
<input type="checkbox"/>	L4	nonlinear adj programming	394
<input type="checkbox"/>	L3	L2 and programming	5
<input type="checkbox"/>	L2	L1 and (nonlinear or (non adj linear\$))	14
<input type="checkbox"/>	L1	5963447	30